

# Academic History

\*\*\*This is Not an Official Transcript\*\*\*

Create Date: 10/22/2020 15:10:03

## General Information

Student: Han, Yunhai

PID: A53307224

Student Level: GR

College: Graduate Division

Major: Engin Scis (Mechanical Engin)

Intended Degree: Master of Science

## Cumulative Summary

| Grade Option | UC-Crdts Attm | Crdts Pssd | UC-GPA Crdts | UC-Grade Points | UC-GPA |
|--------------|---------------|------------|--------------|-----------------|--------|
| Letter       | 44.00         | 44.00      | 44.00        | 172.00          | 3.909  |
| S/U          | 1.00          | 1.00       | 0.00         | 0.00            | 0.000  |
| TOTAL        | 45.00         | 45.00      | 44.00        | 172.00          | 3.909  |

All credits are in quarter units. Cumulative summaries on this record may reflect adjustments for repeated courses and/or other adjustments made in accordance with UCSD academic policies.

## UCSD Graduate Courses by Term

### Term: Fall Qtr 2020

| Subject | Course | Course Title                    | Units | Grade | Points | Repeat |
|---------|--------|---------------------------------|-------|-------|--------|--------|
| CSE     | 276C   | Mathematics for Robotics        | 4.00  |       | 0.00   |        |
| MAE     | 208    | Mathematics for Engineers       | 4.00  |       | 0.00   |        |
| MAE     | 247    | Coop Control/Multi-Agent System | 4.00  |       | 0.00   |        |
| MAE     | 299    | Graduate Research               | 4.00  |       | 0.00   |        |

Term Credits Passed: 0.00 Term GPA: 0.000  
Term Grade Points: 0.00 Academic Status:  
Term GPA Credits: 0.00

### Term: Spring Qtr 2020

| Subject | Course | Course Title                                      | Units | Grade | Points | Repeat |
|---------|--------|---|-------|-------|--------|--------|
| CSE     | 290    | Sem/Computer Sci & Engineering Topics in Robotics | 1.00  | S     | 0.00   |        |
| MAE     | 242    | Robot Motion Planning                             | 4.00  | A     | 16.00  |        |
| MAE     | 281B   | Nonlinear Control                                 | 4.00  | A+    | 16.00  |        |
| MATH    | 271C   | Numerical Optimization                            | 4.00  | A     | 16.00  |        |

Term Credits Passed: 13.00 Term GPA: 4.000  
Term Grade Points: 48.00 Academic Status: Good Standing  
Term GPA Credits: 12.00

### Term: Winter Qtr 2020

| Subject | Course | Course Title                  | Units | Grade | Points | Repeat |
|---------|--------|-------------------------------|-------|-------|--------|--------|
| ECE     | 276A   | Sensing & Estimation Robotics | 4.00  | A     | 16.00  |        |
| MAE     | 145    | Robotic Planning & Estimation | 4.00  | A+    | 16.00  |        |
| MAE     | 281A   | Nonlinear Systems             | 4.00  | A     | 16.00  |        |
| MATH    | 271B   | Numerical Optimization        | 4.00  | A+    | 16.00  |        |

Term Credits Passed: 16.00 Term GPA: 4.000  
Term Grade Points: 64.00 Academic Status: Good Standing  
Term GPA Credits: 16.00

### Term: Fall Qtr 2019

| Subject | Course | Course Title             | Units | Grade | Points | Repeat |
|---------|--------|--------------------------|-------|-------|--------|--------|
| CSE     | 276A   | Introduction to Robotics | 4.00  | A+    | 16.00  |        |

|      |      |                                |      |    |       |  |
|------|------|--------------------------------|------|----|-------|--|
| ECE  | 269  | Linear Algebra and Application | 4.00 | B+ | 13.20 |  |
| MAE  | 280A | Linear Systems Theory          | 4.00 | A  | 16.00 |  |
| MATH | 271A | Numerical Optimization         | 4.00 | A- | 14.80 |  |

Term Credits Passed: 16.00 Term GPA: 3.750  
 Term Grade Points: 60.00 Academic Status: Good Standing  
 Term GPA Credits: 16.00

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